Multiple-Target Tracking with Radar Applications

Samuel S. Blackman

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   Tracking and Sensor Data Fusion Wolfgang Koch,2013-09-20 Sensor Data Fusion is the process of combining incomplete and imperfect pieces of mutually complementary sensor information in such a way that a better understanding of an underlying real world phenomenon is achieved Typically this insight is either unobtainable otherwise or a fusion result exceeds what can be produced from a single sensor output in accuracy reliability or cost This book provides an introduction Sensor Data Fusion as an information technology as well as a branch of engineering science and informatics Part I presents a coherent methodological framework thus providing the prerequisites for discussing selected applications in Part II of the book The presentation mirrors the author s views on the subject and emphasizes his own contributions to the development of particular aspects With some delay Sensor Data Fusion is likely to develop along lines similar to the evolution of another modern key technology whose origin is in the military domain the Internet It is the author s firm conviction that until now scientists and engineers have only scratched the surface of the vast range of opportunities for research engineering and product development that still waits to be explored the Internet of the Sensors   **Vision, Modeling, and Visualization 2008** Oliver Deussen,2008   **Transport Systems Telematics** Jerzy Mikulski,2010-10-23 The idea of telematics appeared more than a decade ago and it is possible to define it in a general and simple way as a communication system for collecting processing and distributing information The transport services market is definitely the most important area for telematic applications Transport telematics issues constitute a field of knowledge of transport that integrates information technology and telecommunications in applications for managing and controlling traffic in transport systems stimulating technical and organizational activities that ensure improved effectiveness and safe operation of such systems Integrated and cooperating telematic applications constitute intelligent transport systems The basis of such systems is to efficiently collect and process information and to manage its flow within the system This enables supplying information from almost all areas of transport activities in real time Intelligent transport supported by a number of integrated telecommunications IT measurement and control engineering solutions and by appropriate tools and software comprises telematic applications They have an extensive range of use in many areas of transport allowing the integration of the means and types of transport including its infrastructure business organization and management processes This monograph is a collection of selected papers presented

at the jubilee transport telematics conference TST 2010 and is the result of the work of many scientists associated with this area of knowledge and who had spent years with the conference *Modern Transport Telematics* Jerzy Mikulski,2011-10-06 This book constitutes the proceedings of the 11th International Conference on Transport Systems Telematics TST 2011 held in Katowice Ustron Poland in October 2011 The 47 papers included in this volume were carefully reviewed and selected for inclusion in this book Transport telematics systems are information technologies that are used in the field of transport including infrastructure vehicles and users Intelligent transport systems are advanced applications that are to provide innovative services for the various modes of transport and traffic management Also they should enable users to be better informed and make safer more coordinated and smarter use of transport networks Telematic services integrate telecommunications electronics and information technology in transport engineering in order to plan design operate maintain and manage transport systems **Radar System Analysis and Modeling** David Knox Barton,2005 Accompanying disc includes an evaluation version of Mathcad11 which will expire 120 days after installation Statistica Sinica ,2009 *Signal Detection and Estimation* Mourad Barkat,2005 This newly revised edition of a classic Artech House book provides you with a comprehensive and current understanding of signal detection and estimation Featuring a wealth of new and expanded material the second edition introduces the concepts of adaptive CFAR detection and distributed CA CFAR detection The book provides complete explanations of the mathematics you need to fully master the material including probability theory distributions and random processes *Digital Techniques for Wideband Receivers* James Tsui,2001 A comprehensive design guide for your digital processing work with today s complex receiver systems It includes information on wideband electronic warfare receivers the ADC testing procedure frequency channelization and decoding schemes and the operation of monobit receivers **American Book Publishing Record** ,1999 Multiple-Target Tracking with Radar Applications Samuel S. Blackman,1986-01-01 *Evaluating Intelligence Systems that Support Deep Fires* Frank A. Camm,Rand Corporation,1989 Current U S Army doctrine emphasizes the importance of extending command emphasis to include not just the close battle but the deep battle It calls for the use of Deep Fires and maneuver to exploit the deep portion of the battlefield This report presents an analytic approach that could simulate the development of combat intelligence about the deep battlefield and compare the performance of alternative intelligence systems to support Deep Fires It emphasizes the development of intelligence products that the Army could use to support the Army tactical missile system in a Central European war in the mid 1990s It draws on observations of combat intelligence activities during several U S and NATO command post exercises in Germany from 1986 to 1988 and on Army approved European scenarios and Army combat and intelligence collection models to provide inputs to the simulation of the intelligence system as a whole The analytic approach presented here employs a set of new techniques for modeling the quality of information in an intelligence system It uses simple Bayesian logic to develop a high level view of intelligence processing and realizes it in a flexible parameterized rule

based network model **Design and Analysis of Modern Tracking Systems** Samuel S. Blackman,Robert Popoli,1999 Here s a thorough overview of the state of the art in design and implementation of advanced tracking for single and multiple sensor systems This practical resource provides modern system designers and analysts with in depth evaluations of sensor management kinematic and attribute data processing data association situation assessment and modern tracking and data fusion methods as applied in both military and non military arenas **Multitarget-multisensor Tracking: Applications and advances** Yaakov Bar-Shalom,1990 **Bayesian Multiple Target Tracking** Praveen Babu Choppala,Victoria University of Wellington. School of Engineering and Computer Science,2014 Bayesian Tracking and Parameter Learning for Non-linear Multiple Target Tracking Models Lan Jiang (Signal processing engineer),Sumeetpal Sidhu Singh,Sinan Yıldırum,2014 **A Bayesian Framework for Target Tracking Using Acoustic and Image Measurements** Volkan Cevher,2005 Target tracking is a broad subject area extensively studied in many engineering disciplines In this thesis target tracking implies the temporal estimation of target features such as the target s direction of arrival DOA the target s boundary pixels in a sequence of images and or the target s position in space For multiple target tracking we have introduced a new motion model that incorporates an acceleration component along the heading direction of the target We have also shown that the target motion parameters can be considered part of a more general feature set for target tracking e g target frequencies which may be unrelated to the target motion can be used to improve the tracking performance We have introduced an acoustic multiple target tracker using a flexible observation model based on an image tracking approach by assuming that the DOA observations might be spurious and that some of the DOAs might be missing in the observation set We have also addressed the acoustic calibration problem from sources of opportunity such as beacons or a moving source We have derived and compared several calibration methods for the case where the node can hear a moving source whose position can be reported back to the node The particle filter as a recursive algorithm requires an initialization phase prior to tracking a state vector The Metropolis Hastings MH algorithm has been used for sampling from intractable multivariate target distributions and is well suited for the initialization problem Since the particle filter only needs samples around the mode we have modified the MH algorithm to generate samples distributed around the modes of the target posterior By simulations we show that this mode hungry algorithm converges an order of magnitude faster than the original MH scheme Finally we have developed a general framework for the joint state space tracking problem A proposal strategy for joint state space tracking using the particle filters is defined by carefully placing the random support of the joint filter in the region where the final posterior is likely to lie Computer simulations demonstrate improved performance and robustness of the joint state space when using the new particle proposal strategy *Multiple Radar Target Tracking in Environments with High Noise and Clutter* Samuel P. Ebenezer,2015 Tracking a time varying number of targets is a challenging dynamic state estimation problem whose complexity is intensifiedunder low signal to noise ratio SNR or high clutter conditions This is important for

example when tracking multiple closely spaced targets moving in the same direction such as aconvoy of low observable vehicles moving through a forest or multipletargets moving in a crisscross pattern The SNR in these applications is usually low as the reflected signals from the targets are weak or the noise level is very high An effective approach for detecting and tracking a single targetunder low SNR conditions is the track before detect filter TBDF that uses unthresholded measurements However the TBDF has only been used to track a small fixed number of targets at low SNR This work proposes a new multiple target TBDF approach to track a dynamically varying number of targets under the recursive Bayesian framework For a given maximum number of targets the state estimates are obtained by estimating the joint multiple target posterior probability density function under all possible target existence combinations The estimation of the corresponding target existence combination probabilities and the target existence probabilities are also derived A feasible sequential Monte Carlo SMC based implementation algorithm is proposed The approximation accuracy of the SMC method with a reduced number of particles is improved by an efficient proposal density function that partitions the multiple target space into a single target space The proposed multiple target TBDF method is extended to track targets in seaclutter using highly time varying radar measurements A generalized likelihood function for closely spaced multiple targets in compound Gaussian sea clutter is derived together with the maximum likelihood estimate of the model parameters using an iterative fixed point algorithm The TBDF performance is improved by proposing a computationally feasible method to estimate the space time covariance matrix of rapidly varying seaclutter The method applies the Kronecker product approximation to the covariance matrix and uses particle filtering to solve the resulting dynamicstate space model formulation   A Bayesian Approach to Tracking Multiple Targets Using Sensor Arrays and Particle Filters Matthew Orton,William J. Fitzgerald,University of Cambridge. Engineering Department,2001

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