

## ROBOTICS

**IRB 120 industrial robot**

## ABB's smallest robot – for flexible and compact

**Compact and lightweight**

An ideal small robot from ABB, the IRB 120 offers all the functionality and expertise of the ABB range in a much smaller package. Its reduced weight of only 265 kg and compact design enables it to be mounted virtually anywhere, whether it is inside a cell, in top of a machine or close to other robots on the production line.

**Multi-purpose**

Ideal for a wide range of industries including the electronic, food and beverage, machinery, solar, pharmaceutical, medical and research sectors, the IRB 120 joins ABB's fourth-generation of new industrial technology.

As with all Clean Room IRB 120 Class D version, it enhances the versatility by making it suitable for environments with stringent cleanliness standards.

**Food Grade Lubrication**

This Food Grade Lubrication (FGL) option includes Clean Room IRB 120 Class D which ensures uncompromising safety and hygiene for food and beverage applications. The Clean Room IRB 120 design eliminates the potential for contamination of the food handling area. This option provides smooth surfaces and special paint for easier cleaning.

**Easy to integrate**

Measuring in at only 265 kg, this robot weighs truly the most compact and easiest to integrate in the market. It can be mounted at any angle without any restriction. The smooth surfaces are easy to clean and the cables for air and customer signals are internally routed all the way from the foot to the wrist, ensuring that integration is effortless.

The IRB 120 robot is the latest addition to ABB's new fourth-generation of robotic technology and ABB's smallest robot ever produced. Ideal for material handling and assembly applications, the new IRB 120 robot provides an agile, compact and lightweight solution with superior control and path accuracy.

**Optimized working range**

In addition to a horizontal reach of 2.80 m, the robot has fast in-plane strokes and the ability to reach 3.12-m below its base. Furthermore, the IRB 120 has a very compact turning radius, which is enabled by the robot's symmetrical architecture, without offset on axis 2. This ensures the robot can be mounted close to other equipment and the slim vertical timelines the arm to reach closer to the application.

**Fast, accurate and agile**

Designed with a light, aluminum structure, the powerful compact motions ensure the robot is enabled with a fast acceleration, and can deliver accuracy and agility in any application. Using the IRB 120's variant, Opti-Motion, can be reduced up to 25%, where the workpiece needs alternative re-orientations, and tools A, B and C are predominantly used. This faster variation is well suited for pick and place, assembly and guided operations, together with Pick & Place in 3D.

**IRB 120 Compact controller – optimised for small robots** ABB's new IRB 120 compact controller takes the capabilities of the extremely powerful IRB 6 controller and presents them in a truly compact format.

The new Compact controller brings accuracy and motion control to applications, which previously had been exclusive to large installations.

In addition to standard servo drives, the new controller also enables easy commissioning through one-phase power input, no external connectors for all signals and a built-in expandable I/O (16 DI, 16 DO, 1/4AO).

# Abb Robot Programming Manuals Irb

**Roman Szewczyk,Cezary  
Zieliński,Małgorzata Kaliczyńska**

## **Abb Robot Programming Manuals Irb:**

*Computer Integrated Manufacturing (Iccim '91): Manufacturing Enterprises Of The 21st Century - Proceedings Of The International Conference* B S Lim,1991-10-02 In the 21st century computer integrated manufacturing CIM systems will not only be the economic development tools but will also be the essential means of achieving a higher level of flexibility cohesiveness and performance CIM systems are beginning to settle into our society and industries with greater emphasis on the integration of economic cultural and social aspects together with design planning factory automation and artificial intelligent systems This volume of proceedings brings together 10 keynote and invited speaker addresses and over 180 papers by practitioners from 28 countries It documents current research and in depth studies on the fundamental aspects of advanced CIM systems and their practical applications The papers fall into 3 main sections CIM Related Issues Industrial AI Applications Aspects and Concurrent Engineering Advanced Design Simulation and Flexible Manufacturing Systems

**Industrial Robotics** ,2004    [CAD/CAM, Robotics and Factories of the Future](#) Dipak Kumar Mandal,Chanan Singh Syan,2016-01-05 This volume is based on the proceedings of the 28th International Conference on CAD CAM Robotics and Factories of the Future This book specially focuses on the positive changes made in the field of robotics CAD CAM and future outlook for emerging manufacturing units Some of the important topics discussed in the conference are product development and sustainability modeling and simulation automation robotics and handling systems supply chain management and logistics advanced manufacturing processes human aspects in engineering activities emerging scenarios in engineering education and training The contents of this set of proceedings will prove useful to both researchers and practitioners

**Journal of Engineering for Industry** ,1996    **Recent Advances in Systems, Control and Information Technology** Roman Szewczyk,Małgorzata Kaliczyńska,2016-11-29 This book presents the proceedings of the International Conference on Systems Control and Information Technologies 2016 It includes research findings from leading experts in the fields connected with INDUSTRY 4.0 and its implementation especially intelligent systems advanced control information technologies industrial automation robotics intelligent sensors metrology and new materials Each chapter offers an analysis of a specific technical problem followed by a numerical analysis and simulation as well as the implementation for the solution of a real world problem

**Robot 2015: Second Iberian Robotics Conference** Luís Paulo Reis,António Paulo Moreira,Pedro Lima,Luis Montano,Victor Munoz Martinez,2015-11-27 This book contains a selection of papers accepted for presentation and discussion at ROBOT 2015 Second Iberian Robotics Conference held in Lisbon Portugal November 19th 21th 2015 ROBOT 2015 is part of a series of conferences that are a joint organization of SPR Sociedade Portuguesa de Robótica Portuguese Society for Robotics SEIDROB Sociedad Espa ola para la Investigaci n y Desarrollo de la Rob tica Spanish Society for Research and Development in Robotics and CEA GTRob Grupo Tem tico de Rob tica Robotics Thematic Group The conference organization had also the collaboration of several universities and research institutes including University of

Minho University of Porto University of Lisbon Polytechnic Institute of Porto University of Aveiro University of Zaragoza University of Malaga LIACC INESC TEC and LARSyS Robot 2015 was focussed on the Robotics scientific and technological activities in the Iberian Peninsula although open to research and delegates from other countries The conference featured 19 special sessions plus a main general robotics track The special sessions were about Agricultural Robotics and Field Automation Autonomous Driving and Driver Assistance Systems Communication Aware Robotics Environmental Robotics Social Robotics Intelligent and Adaptable AAL Systems Future Industrial Robotics Systems Legged Locomotion Robots Rehabilitation and Assistive Robotics Robotic Applications in Art and Architecture Surgical Robotics Urban Robotics Visual Perception for Autonomous Robots Machine Learning in Robotics Simulation and Competitions in Robotics Educational Robotics Visual Maps in Robotics Control and Planning in Aerial Robotics the XVI edition of the Workshop on Physical Agents and a Special Session on Technological Transfer and Innovation

### **Automation 2020: Towards Industry of the Future**

Roman Szewczyk,Cezary Zieliński,Małgorzata Kaliczyńska,2020-02-27 This book presents the scientific outcomes of the International Conference AUTOMATION 2020 held on March 18 20 2020 in Warsaw Poland The next 30 years will see radical innovations in production processes transportation management and social life The changes brought about by the transformation to zero emission industry require advances in many fields but especially in industrial automation robotics and measurement techniques associated with the cyber physical systems employing artificial intelligence that will be key to reducing costs and enabling European society to maintain its quality of live In this context the book features the latest research toward further developing these fields of engineering and also offers solutions and guidelines that are useful for both researchers and engineers addressing problems associated with the world of ongoing radical changes

### **AI and IoT:**

**Driving Business Success and Sustainability in the Digital Age** Bahaa Awwad,2025-09-26 This book embarks on a transformative journey that explores the powerful convergence of artificial intelligence AI Internet of Things IoT and business management With the advent of these cutting edge technologies businesses have unprecedented opportunities to revolutionize their operations drive innovation and achieve remarkable success in today s digital landscape

### **Industrial**

**Motion Control** Dr. Hakan Gurocak,2016-03-14 Motion control is widely used in all types of industries including packaging assembly textile paper printing food processing wood products machinery electronics and semiconductor manufacturing Industrial motion control applications use specialized equipment and require system design and integration To design such systems engineers need to be familiar with industrial motion control products be able to bring together control theory kinematics dynamics electronics simulation programming and machine design apply interdisciplinary knowledge and deal with practical application issues The book is intended to be an introduction to the topic for senior level undergraduate mechanical and electrical engineering students It should also be resource for system design engineers mechanical engineers electrical engineers project managers industrial engineers manufacturing engineers product managers field engineers and

programmers in industry      **Proceedings** Thomas Lund,1990      **The National Guide to Educational Credit for Training Programs** American Council on Education,2005 Highlights over 6 000 educational programs offered by business labor unions schools training suppliers professional and voluntary associations and government agencies      **Proceedings** ,2002      **Robot Control 2000 (SYROCO'00)** Peter Kopacek,2001 This Proceedings contains the papers presented at the sixth IFAC Symposium on Robot Control 2000 SYROCO 00 held in Vienna Austria on 21 23 September 2000 The contributions cover the whole field of robot control starting with the classical subjects like non linear robust and hybrid control force and tracking control modelling and identification simulation and education neutral and fuzzy control But new robot applications require new robot concepts and new control tasks In consequence most of the contributions deal with mobile intelligent robots and multiple robot systems but also new applications like disassembly One of the fastest growing fields in the last three years is development and control of robots for entertainment leisure and hobby In four survey papers the state of the art in robot control and further developing trends were emphasised Because the field of robotics is growing up today in smaller countries two presentations deal with robots in Brazil and Macedonia The very important field of sensor fusion and an industrial view of future developments in robot control were also topics of survey papers      *Sheet Metal Industries* ,1995      *Proceedings of the 1999 IEEE International Conference on Control Applications* ,1999      **Intelligent Robots and Computer Vision XVI** Society of Photo-optical Instrumentation Engineers,1997      **Welding and Metal Fabrication** ,1993      *Robotica* ,1995      The Specifications and Applications of Industrial Robots in Japan ,1997  
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