

# Advances in Intelligent Vehicles



Intelligent Systems Series

Yaobin Chen  
Lingxi Li



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## **Advances In Intelligent Vehicles Author Yaobin Chen Dec 2013:**

**Advances in Intelligent Vehicles** Yaobin Chen, 2017-08-08 *Advances in Intelligent Vehicles* By Yaobin Chen

*Advances in Intelligent Vehicles* Yaobin Chen, Lingxi Li, 2014-03-20 *Advances in Intelligent Vehicles* presents recent advances in intelligent vehicle technologies that enhance the safety reliability and performance of vehicles and vehicular networks and systems This book provides readers with up to date research results and cutting edge technologies in the area of intelligent vehicles and transportation systems Topics covered include virtual and staged testing scenarios collision avoidance human factors and modeling techniques The Series in Intelligent Systems publishes titles that cover state of the art knowledge and the latest advances in research and development in intelligent systems Its scope includes theoretical studies design methods and real world implementations and applications Provides researchers and engineers with up to date research results and state of the art technologies in the area of intelligent vehicles and transportation systems Covers hot topics including driver assistance systems cooperative vehicle highway systems collision avoidance pedestrian protection image radar and lidar signal processing and V2V and V2I communications *Autonomous Intelligent Vehicles* Hong

Cheng, 2011-11-15 This important text reference presents state of the art research on intelligent vehicles covering not only topics of object obstacle detection and recognition but also aspects of vehicle motion control With an emphasis on both high level concepts and practical detail the text links theory algorithms and issues of hardware and software implementation in intelligent vehicle research Topics and features presents a thorough introduction to the development and latest progress in intelligent vehicle research and proposes a basic framework provides detection and tracking algorithms for structured and unstructured roads as well as on road vehicle detection and tracking algorithms using boosted Gabor features discusses an approach for multiple sensor based multiple object tracking in addition to an integrated DGPS IMU positioning approach examines a vehicle navigation approach using global views introduces algorithms for lateral and longitudinal vehicle motion control

Recent Advance in Intelligent Vehicle Biao Yu, Linglong Lin, Jiajia Chen, 2024-07-17 The aim of this reprint is to immerse the reader in the latest technologies in autonomous vehicles including environment perception technologies planning and control technologies and so on In this reprint leading experts in the field share their state of the art works insights and visions for the future Together we embark on a journey to unlock the full potential of the intelligence in autonomous vehicles seeking sustainable solutions that improve the safety comfort intelligent performance Advanced Motion Control and Sensing for Intelligent Vehicles Li Li, Fei-Yue Wang, 2007-11-24 *Advanced Motion Control and Sensing for Intelligent Vehicles* provides the latest information in intelligent vehicle control sensing and intelligent transportation It addresses the growing need for safe comfortable time and energy efficient modes of transportation with emphasis on the latest key findings current trends and likely future developments in this rapidly expanding field Highlights Discusses individual vehicle dynamics sensory and multiple ground vehicle interactions Includes systematic review of past and current

research achievements Presents case studies in cutting edge directions such as vehicle steering motion vehicle vision systems cooperative driving intersection safety and tire pressure monitoring Assesses the likely future developments of this field This book is useful for both practicing engineers and researchers in the automotive industry Intelligent Vehicles Felipe Jiménez,2017-09-08 Intelligent Road Vehicles examines specific aspects of intelligent vehicles such as enabling technologies human factors and an analysis of social and economic impacts The book is an invaluable resource for those pursuing deeper knowledge in the intelligent vehicles field providing readers with an idea of current and future technologies current projects and developments and the future of intelligent vehicles Intelligent road vehicles are becoming a challenging area of research worldwide Apart from the final applications and systems in vehicles there are many enabling technologies that should be introduced Communications and automation are two key areas for future automobiles This book benefits from collaboration on the Thematic Network on Intelligent Vehicles led by Felipe Jimenez Provides a general overview of different aspects related to intelligent road vehicles sensors applications communications automation human factors etc Addresses the different components and building blocks of intelligent vehicles in a single comprehensive reference Explains how sensors are interpreted including how different sensor readings are fused Addresses issues involved with avoiding collisions and other factors such as pot holes unclear road lines or markings and unexpected weather conditions **Intelligent Transportation Vehicles** Max Suell Dutra,Omar Lengerke,2011-09-09 Intelligent transportation vehicles brings the latest advances and developments in intelligent vehicles to readers on the basis of their significance and quality Wider dissemination of research developments will stimulate more exchanges and collaborations among the research community and contribute to further advancement of this rapidly growing field This Ebook series includes key contributions presented by different researchers These contributions represent a wide coverage of the state of the art and the emerging research directions in intelligent transportation vehicles A cura dell editore Decision Making, Planning, and Control Strategies for Intelligent Vehicles Haotian Cao,Mingjun Li,Song Zhao,Xiaolin Song,2020-07-28 The intelligent vehicle will play a crucial and essential role in the development of the future intelligent transportation system which is developing toward the connected driving environment ultimate driving safety and comforts as well as green efficiency While the decision making planning and control are extremely vital components of the intelligent vehicle these modules act as a bridge connecting the subsystem of the environmental perception and the bottom level control execution of the vehicle as well This short book covers various strategies of designing the decision making trajectory planning and tracking control as well as share driving of the human automation to adapt to different levels of the automated driving system More specifically we introduce an end to end decision making module based on the deep Q learning and improved path planning methods based on artificial potentials and elastic bands which are designed for obstacle avoidance Then the optimal method based on the convex optimization and the natural cubic spline is presented As for the speed planning planning methods based on the multi object optimization and high order

polynomials and a method with convex optimization and natural cubic splines are proposed for the non vehicle following scenario e g free driving lane change obstacle avoidance while the planning method based on vehicle following kinematics and the model predictive control MPC is adopted for the car following scenario We introduce two robust tracking methods for the trajectory following The first one based on nonlinear vehicle longitudinal or path preview dynamic systems utilizes the adaptive sliding mode control SMC law which can compensate for uncertainties to follow the speed or path profiles The second one is based on the five degrees of freedom nonlinear vehicle dynamical system that utilizes the linearized time varying MPC to track the speed and path profile simultaneously Toward human automation cooperative driving systems we introduce two control strategies to address the control authority and conflict management problems between the human driver and the automated driving systems Driving safety field and game theory are utilized to propose a game based strategy which is used to deal with path conflicts during obstacle avoidance Driver s driving intention situation assessment and performance index are employed for the development of the fuzzy based strategy Multiple case studies and demos are included in each chapter to show the effectiveness of the proposed approach We sincerely hope the contents of this short book provide certain theoretical guidance and technical supports for the development of intelligent vehicle technology

*Handbook of Intelligent Vehicles* Azim Eskandarian,2012-02-26 The Handbook of Intelligent Vehicles provides a complete coverage of the fundamentals new technologies and sub areas essential to the development of intelligent vehicles it also includes advances made to date challenges and future trends Significant strides in the field have been made to date however so far there has been no single book or volume which captures these advances in a comprehensive format addressing all essential components and subspecialties of intelligent vehicles as this book does Since the intended users are engineering practitioners as well as researchers and graduate students the book chapters do not only cover fundamentals methods and algorithms but also include how software hardware are implemented and demonstrate the advances along with their present challenges Research at both component and systems levels are required to advance the functionality of intelligent vehicles This volume covers both of these aspects in addition to the fundamentals listed above *Intelligent Vehicle* Ming Xie,Hui Chen,Zhencheng Hu,2021 This book provides a broad introduction to the three key modules behind the design and development of intelligent vehicles for the ultimate purpose of actively ensuring driving safety as well as preventing accidents from all possible causes Self contained and unified in presentation the book explains in detail the fundamental solutions of vehicle perception vehicle decision making and vehicle action taking in a pedagogic order Besides the fundamental knowledge and concepts of intelligent vehicle s perception decision and action this book includes a comprehensive set of real life application scenarios in which intelligent vehicles will play a major role or contribution These case studies of real life applications will help motivate students to learn this exciting subject With concise and simple explanations and boasting a rich set of graphical illustrations the book is an invaluable source for both undergraduate and

postgraduate courses on automotive engineering mechanical engineering and robotics In addition the book will help strengthen the knowledge and skills of young researchers who want to venture into the research and development of intelligent vehicles of the future Intelligent Transportation Vehicles Bentham Science Publishers,2011-09-09

Mechatronics Series I Intelligent Transportation Vehicles brings the latest advances and developments in intelligent vehicles to readers on the basis of their significance and quality Wider dissemination of research developments will stimulate more exchange **Integrated Intelligent Vehicle Dynamics and Control** Wuwei Chen,Hongbo Wang,2025-09-23 The development of intelligent vehicles and connected autonomous vehicles has significantly changed the traffic environment In recent developments automated vehicles and human driven vehicles have started to coexist on roads These new change has brought about new scientific and technological challenges for academia and industry Intelligent vehicle dynamics and control should respond to face these new issues to enhance vehicles functional design and performance The integration of intelligent vehicle dynamics and control is important to understand vehicle dynamics behavior and provide a basis for a control strategy and algorithm design The aim of the Special Issue is to present original papers concerned with integrated intelligent vehicle dynamics and control

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