

PRECISION
MACHINERY
AND ROBOTICS
Volume 2

ACTUATORS FOR CONTROL

Edited by

Hiroyasu Funakubo



CRC Press
Taylor & Francis Group

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Vol 2

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Frequency-Agile Antennas for Wireless Communications Aldo Petosa, 2013-11-01 Mobile data subscriptions are expected to more than double and mobile wireless traffic to increase by more than tenfold over the next few years Proliferation of smart phones tablets and other portable devices are placing greater demands for services such as web browsing global positioning video streaming and video telephony Many of the proposed solutions to deal with these demands will have a significant impact on antenna designs Antennas with frequency agility are considered a promising technology to help implement these new solutions This book provides readers with a sense of the capabilities of frequency agile antennas FAAs the widely diverse methods for achieving tunability the current achievable performance and the challenges still facing FAA designs This resource explores the many aspects of FAAs including an examination of the metrics used to evaluate their performance a review of the most commonly used antenna elements an in depth look at the wide variety of mechanisms for achieving tunability and a comprehensive survey of diverse examples of FAA designs The focus is on FAAs for wireless mobile communications with applications including handsets laptops wireless machine to machine communications as well as larger fixed designs such as cellular base station antennas

Design, Modeling and Experiments of 3-DOF Electromagnetic Spherical Actuators Liang Yan, I-Ming Chen, Chee Kian Lim, Guilin Yang, Kok-Meng Lee, 2011-06-06 A spherical actuator is a novel electric device that can achieve 2 3 DOF rotational motions in a single joint with electric power input It has advantages such as compact structure low mass moment of inertia fast response and non singularities within the workspace It has promising applications in robotics automobile manufacturing medicine and aerospace industry This is the first monograph that introduces the research on spherical actuators systematically It broadens the scope of actuators from conventional single axis to multi axis which will help both beginners and researchers to enhance their knowledge on electromagnetic actuators Generic analytic modeling methods for magnetic field and torque output are developed which can be applied to the development of other electromagnetic actuators A parametric design methodology that allows fast analysis and design of spherical actuators for various applications is proposed A novel non contact high precision 3 DOF spherical motion sensing methodology is developed and evaluated with experiments which shows that it can achieve one order of magnitude higher precision than conventional methods The technologies of nondimensionalization and normalization are introduced into magnetic field analysis the first time and a benchmark database is established for the reference of other researches on spherical actuators

Proceedings of the ASME International Design Engineering Technical Conferences and Computers and Information in Engineering Conferences--2005, 2005 Robotics Yokyo Matsuoka, Hugh Durrant-Whyte, Jose Neira, 2011-08-05 Papers from a flagship robotics conference that cover topics ranging from kinematics to human robot interaction and robot perception Robotics Science and Systems VI spans a wide spectrum of robotics bringing together researchers working on the foundations of robotics robotics applications and the analysis of robotics

systems This volume presents the proceedings of the sixth Robotics Science and Systems conference held in 2010 at the University of Zaragoza Spain The papers presented cover a wide range of topics in robotics spanning mechanisms kinematics dynamics and control human robot interaction and human centered systems distributed systems mobile systems and mobility manipulation field robotics medical robotics biological robotics robot perception and estimation and learning in robotic systems The conference and its proceedings reflect not only the tremendous growth of robotics as a discipline but also the desire in the robotics community for a flagship event at which the best of the research in the field can be presented

Proceedings of the ... ASME Design Engineering Technical Conferences ,2005 *Applied Mechanics Reviews* ,1989

Advanced Engineering and Computational Methodologies for Intelligent Mechatronics and Robotics Sirouspour, Shahin,2013-03-31 The emergence of mechatronics has advanced the engineering disciplines producing a plethora of useful technical systems *Advanced Engineering and Computational Methodologies for Intelligent Mechatronics and Robotics* presents the latest innovations and technologies in the fields of mechatronics and robotics These innovations are applied to a wide range of applications for robotic assisted manufacturing complex systems and many more This publication is essential to bridge the gap between theory and practice for researchers engineers and practitioners from academia to government

Microrobotics Yves Bellouard,2009-11-04 From conception to realization *Microrobotics Methods and Applications* covers all aspects of miniaturized systems that physically interact and manipulate objects at the microscale It provides a solid understanding of this multidisciplinary field which combines areas of materials science mechanical engineering and applied physics Requiring no *ICMIT 2005* ,2005 **Mobile Robots for Digital Farming** Redmond R. Shamshiri,Ibrahim A. Hameed,2024-09-09 This book provides a complete and comprehensive reference for agricultural mobile robots covering all aspects of the design process from sensing and perceiving to planning and acting for practical farming applications *Mobile Robots for Digital Farming* explores topics such as Robot Operating Systems ROS dynamic simulation artificial intelligence image processing and machine learning Additionally it features multiple case studies from funded projects and real field trials This book will be useful for professors and academics in various engineering disciplines mechanical robotics control electrical computer and agricultural graduate and undergraduate students farmers commercial growers startups private companies consultancy agencies equipment suppliers and agricultural policymakers *Flexible Constant-Force Robotic Manipulators* Qingsong Xu,2025-11-25 *Flexible Constant Force Robotic Manipulators Design and Applications* offers a comprehensive survey of recent designs of flexible constant force robotic manipulators focusing on their applications in biomedical fields It presents innovative design approaches including flexure mechanisms and bistable beams that enable compliant constant force and constant torque motion Key topics include constant force gripper designs for biological sample manipulation polishing end effectors for robotic manufacturing and manipulators for ultrasound imaging that maintain consistent contact with the human body This book defines the roles of these manipulators in biological cell manipulation part

polishing ultrasound imaging and healthcare aiming to improve the quality of life It is suitable for beginners providing fundamental principles of compliant mechanism based flexible robotics and for advanced audiences offering in depth descriptions of state of the art techniques Readers will gain insights into the current limitations and future directions of robotic technology in precision medical treatment making it a valuable resource for both newcomers and experienced professionals in the field Provides new mechanism designs of flexible constant force robotic manipulators for precision medical applications Contains both theoretical and experimental results of constant force robotic manipulators with color figure illustrations Examples provide the reader with additional practice in the design modeling and implementation of flexible robotic devices in real life applications International Conference on Advancements of Medicine and Health Care through Technology; 29th August - 2nd September 2011, Cluj-Napoca, Romania Simona Vlad,Radu V. Ciupa,2011-07-25 This volume presents the contributions of the third International Conference on Advancements of Medicine and Health Care through Technology Meditech 2011 held in in Cluj Napoca Romania The papers of this Proceedings volume present new developments in Health Care Technology Medical Devices Measurement and Instrumentation Medical Imaging Image and Signal Processing Modeling and Simulation Molecular Bioengineering Biomechanics **Optomechatronic Actuators and Manipulation** Kee S. Moon,2005 Proceedings of SPIE present the original research papers presented at SPIE conferences and other high quality conferences in the broad ranging fields of optics and photonics These books provide prompt access to the latest innovations in research and technology in their respective fields Proceedings of SPIE are among the most cited references in patent literature Proceedings of the ... International Symposium on Micromechatronics and Human Science ,2003 **Index to IEEE Publications** Institute of Electrical and Electronics Engineers,1998 Issues for 1973 cover the entire IEEE technical literature Proceedings of the International Symposium on Manufacturing Science and Technology for the 21st Century Zhou Zhaoying,1994 *Journal of Mechanisms, Transmissions, and Automation in Design* ,1985 *ASME Technical Papers* ,1984 **Researchers** Shin Gijutsu Kaihatsu Jigyōdan (Japan),1993 Includes governmental policy development science and technology environmental finance health and welfare industrial agriculture forestry and fisheries international trade transportation telecommunications labor construction and home affairs agencies Proceedings of the ... IEEE International Conference on Electronics, Circuits, and Systems ,1998

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