



Autodesk® Inventor® 2024
Introduction to Solid Modeling - Part 2
Learning Guide
Mixed Units – 1st Edition

Autodesk Inventor 2013 Introduction To Solid Modeling

Part 2

Randy Shih

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[Tools for Design Using AutoCAD 2013 and Autodesk Inventor 2013](#) Randy Shih,2012-06-21 Tools for Design is intended to provide the user with

an overview of computer aided design using two popular CAD software packages from Autodesk AutoCAD and Autodesk Inventor This book explores the strengths of each package and show how they can be used in design both separately and in combination with each other What you ll learn How to create and dimension 2D multiview drawings using AutoCAD How to freehand sketch using axonometric oblique and perspective projection techniques How to create 3D parametric models and 2D multiview drawings using Autodesk Inventor How to reuse design information between AutoCAD and Autodesk Inventor How to combine parts into assemblies including assembly modeling with a LEGO MINDSTORMS Education Base Set with TETRIX kit and a VEX Robot Kit How to perform basic finite element stress analysis using Inventor Stress Analysis Module

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robot design An unassembled version of the same robot used throughout the book can be bundled with the book No previous experience with Computer Aided Drafting CAD is needed since this book starts at an introductory level The author begins by getting you familiar with the Inventor interface and its basic tools You will start by learning to model simple robot parts and before long you will graduate to creating more complex parts and multi view drawings Along the way you will learn the fundamentals of parametric modeling through the use of geometric constraints and relationships You will also become familiar with many of Inventor's powerful tools and commands that enable you to easily construct complex features in your models Also included is coverage of gears gear trains and spur gear creation using Autodesk Inventor This book continues by examining the different mechanisms commonly used in walking robots You will learn the basic types of planar four bar linkages commonly used in mechanical designs and how to use the GeoGebra Dynamic Geometry software to simulate and analyze 2D linkages Using the knowledge you gained about linkages and mechanism you will learn how to modify your robot and change its behavior by modifying or creating new parts In the final chapter of this book you learn how to combine all the robot parts into assemblies and then run motion analysis You will finish off your project by creating 3D animations of your robot in action There are many books that show you how to perform individual tasks with Autodesk Inventor but this book takes you through an entire project and shows you the complete engineering process By the end of this book you will have modeled and assembled nearly all the parts that make up the TAMIYA Mechanical Tiger and can start building your own robot

[Autodesk Inventor 2018](#) ,2017 Through a hands on practice intensive curriculum this book will teach you the key skills and knowledge needed to design models using Autodesk Inventor starting with conceptual sketching through to solid modeling assembly design and drawing production

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